

Fig. 1

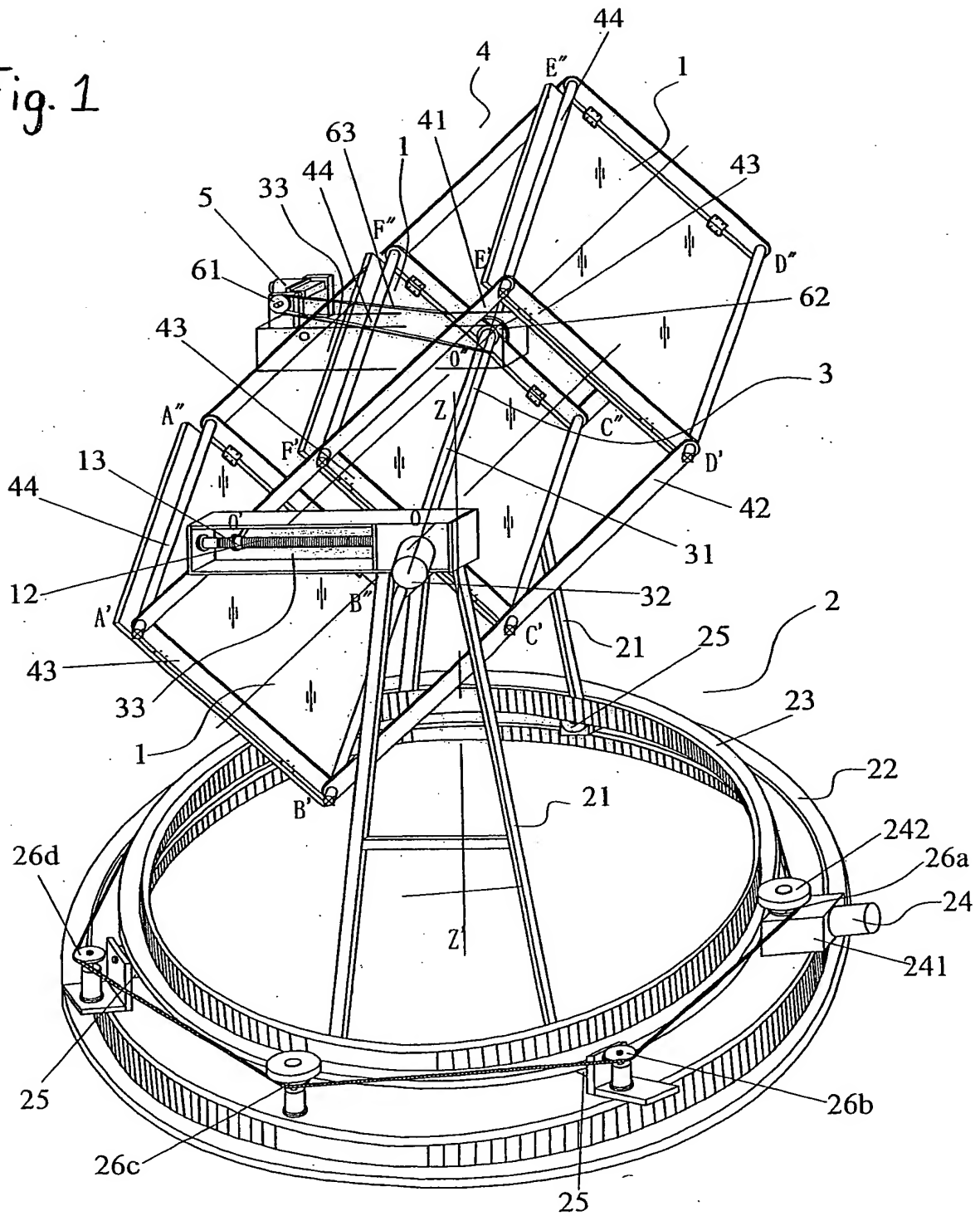
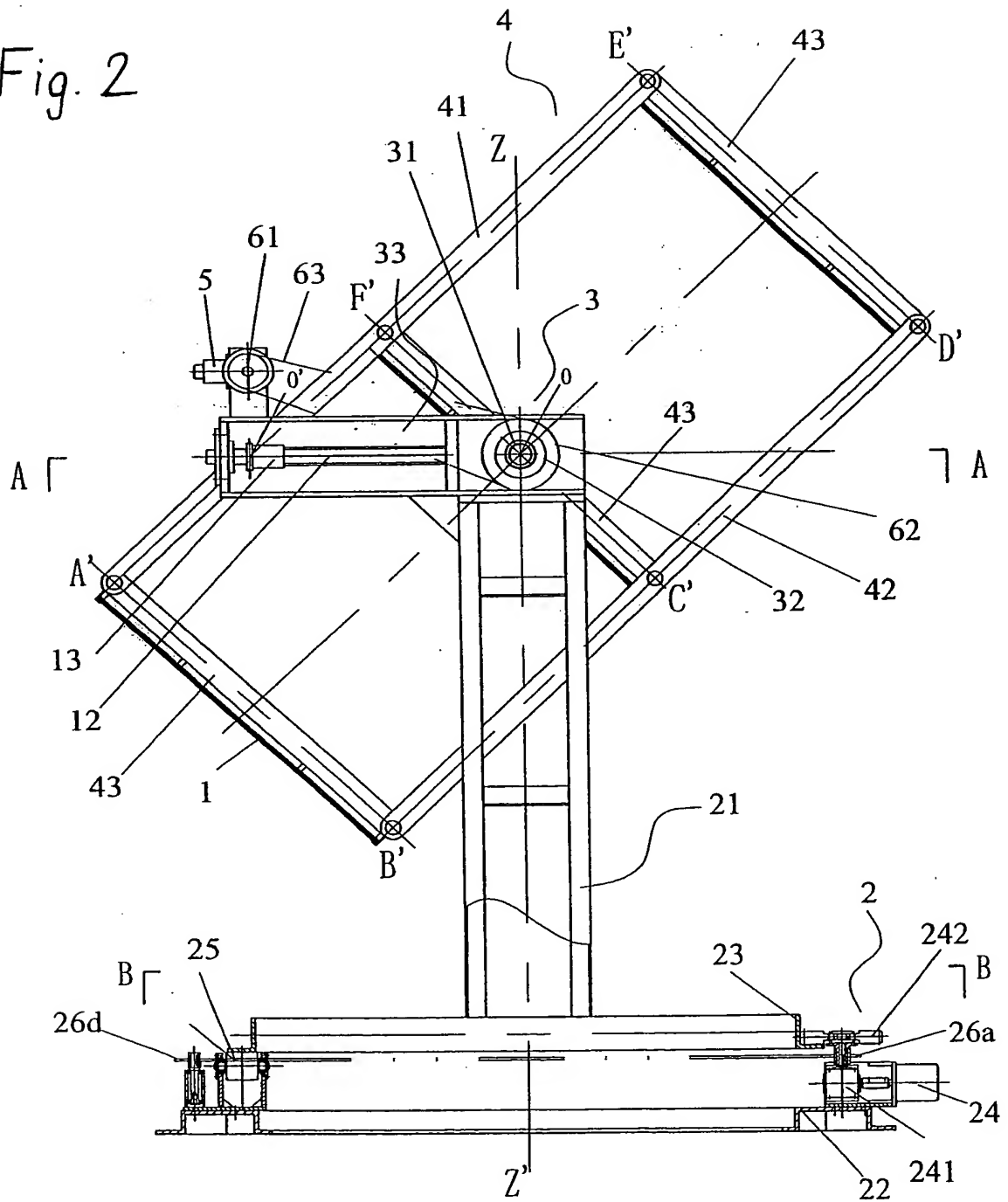


Fig. 2



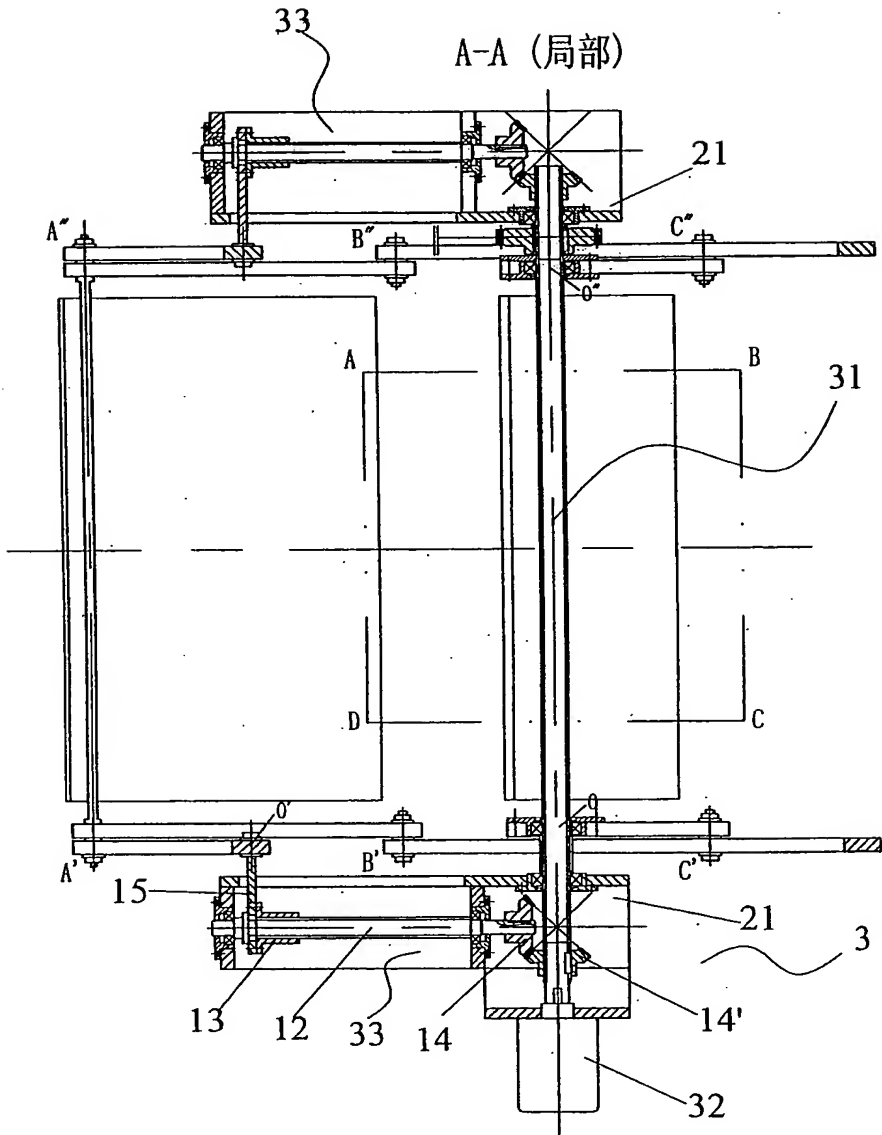


Fig. 3

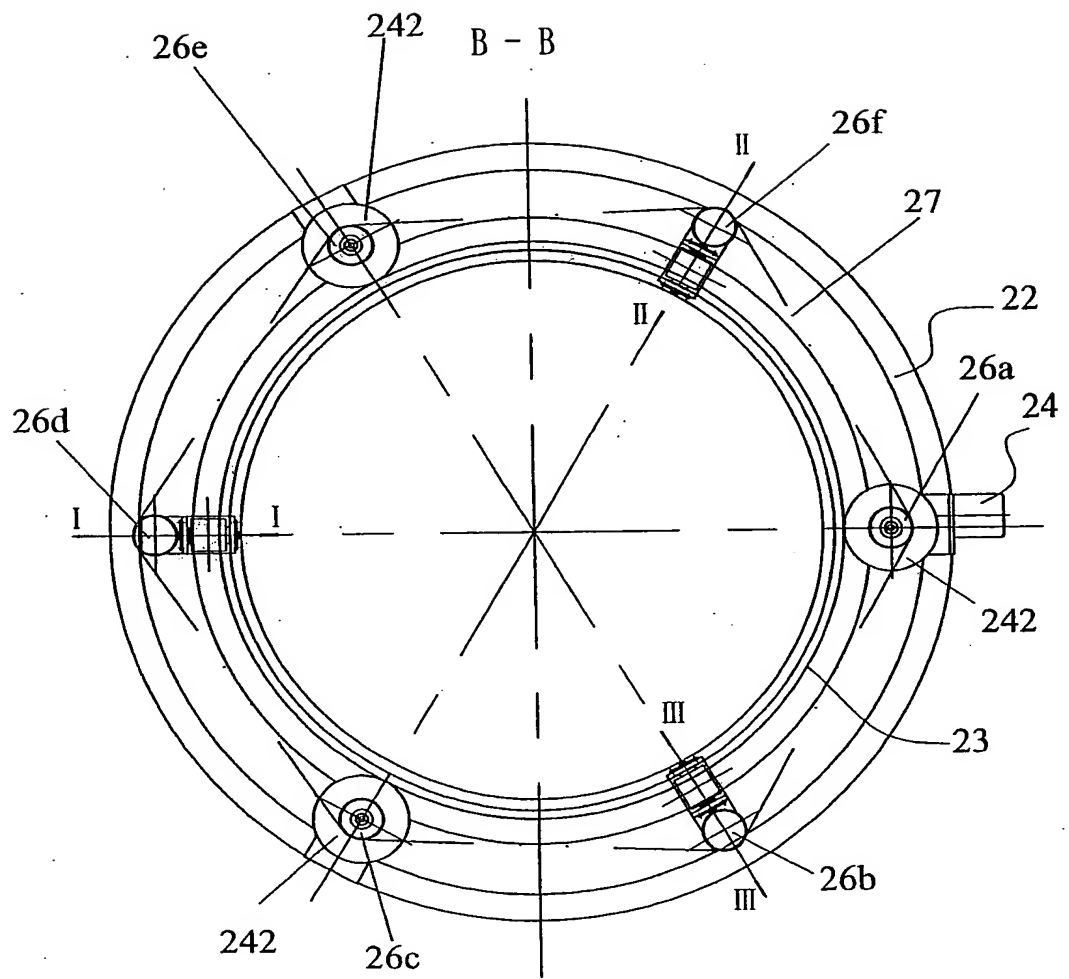


Fig. 4

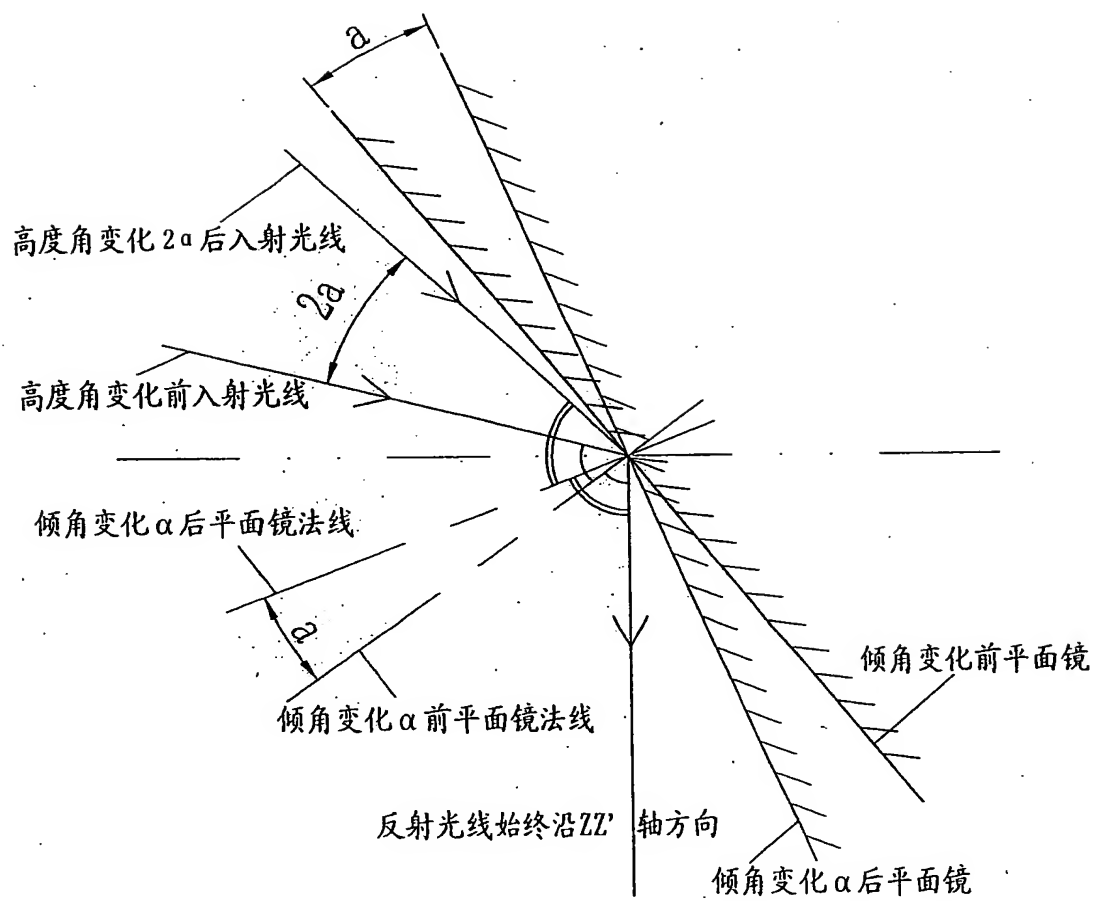


Fig. 5

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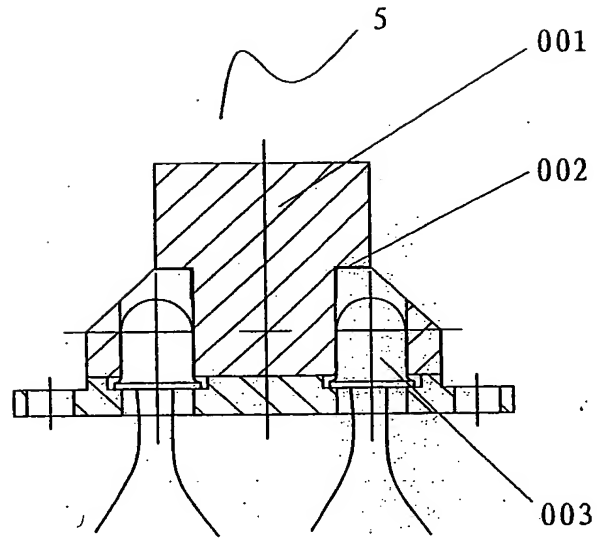


Fig. 6A

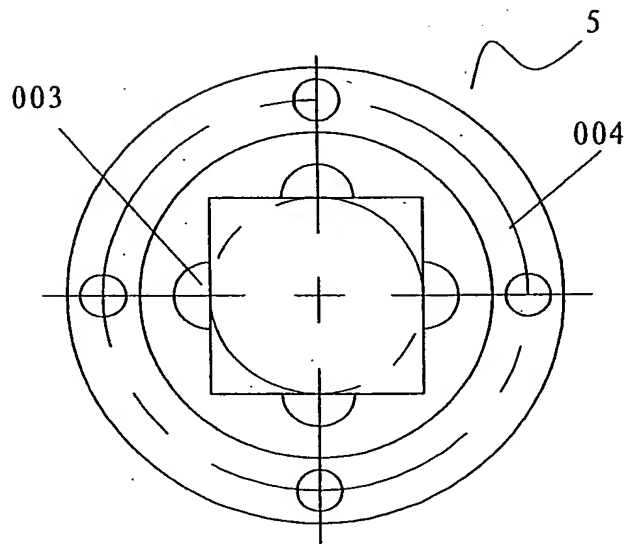


Fig. 6B

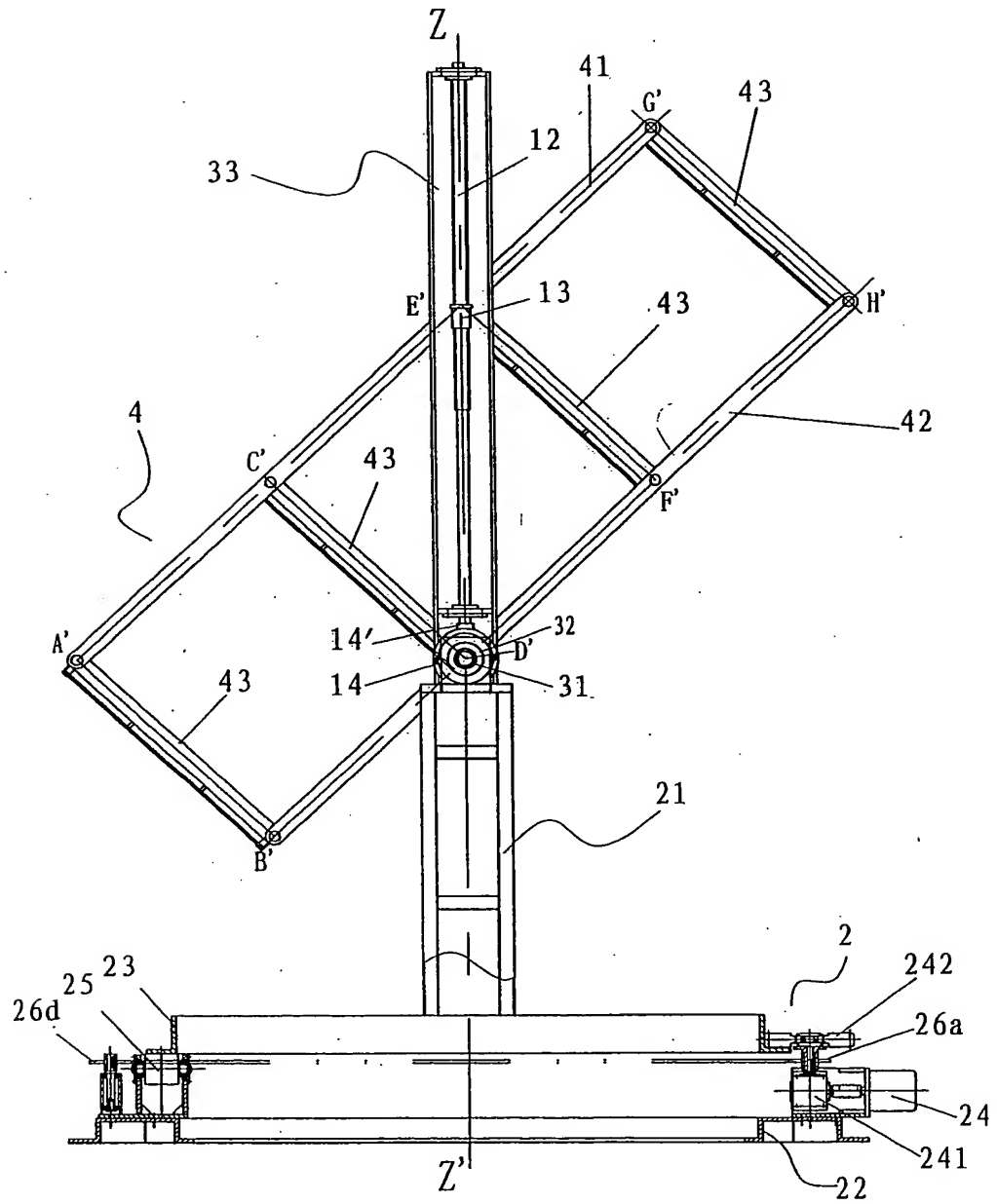


Fig. 7

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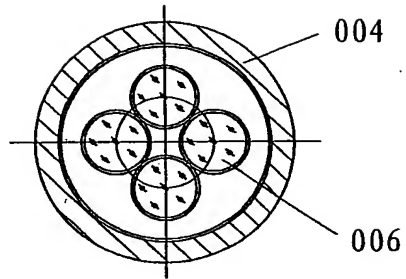


Fig. 8A

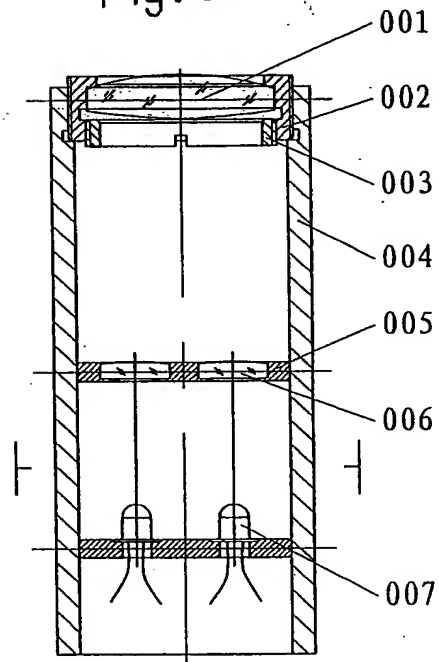


Fig. 8B

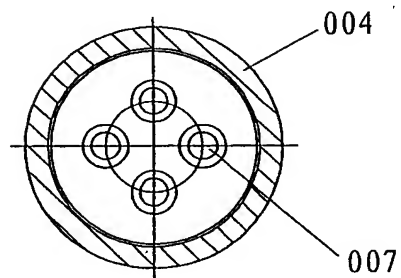
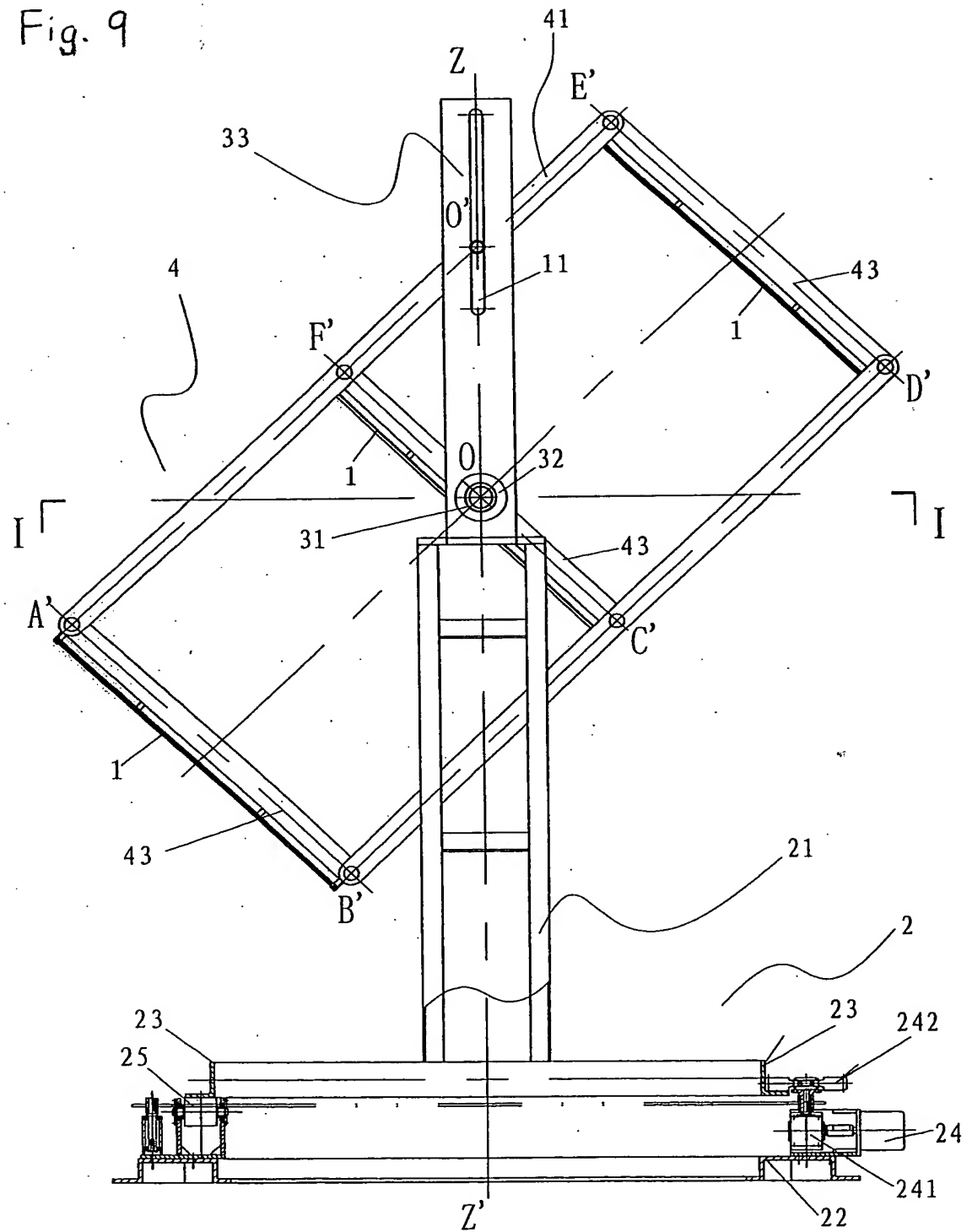


Fig. 8C

Fig. 9



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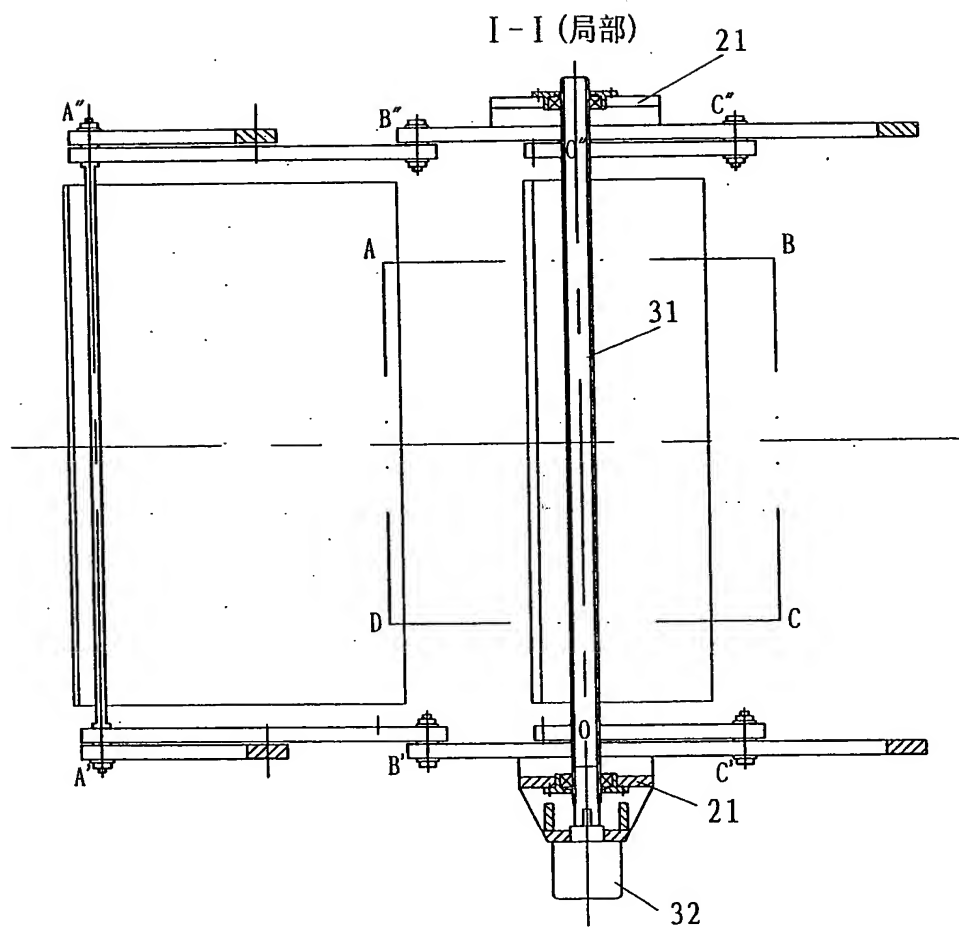


Fig. 10

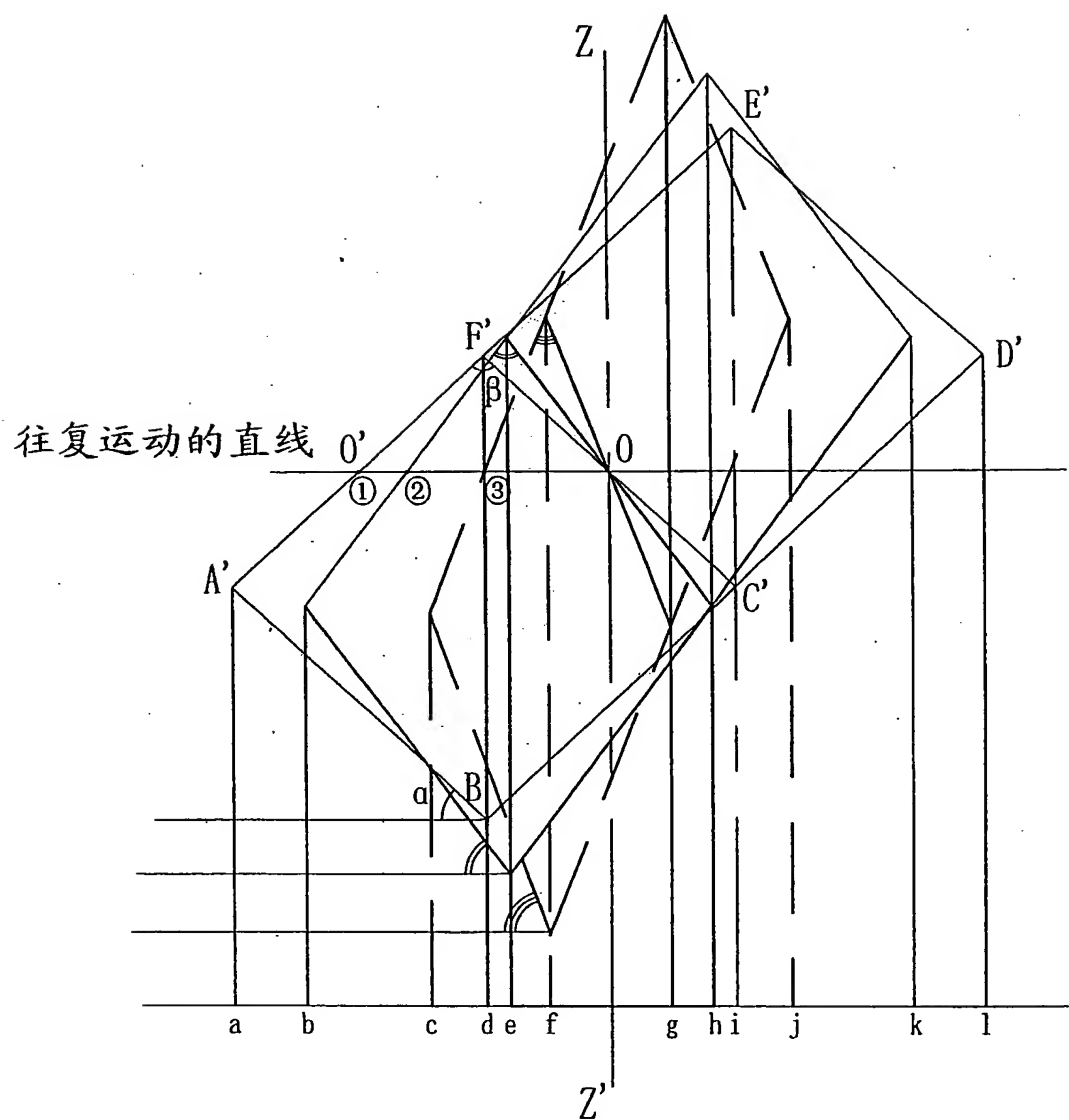
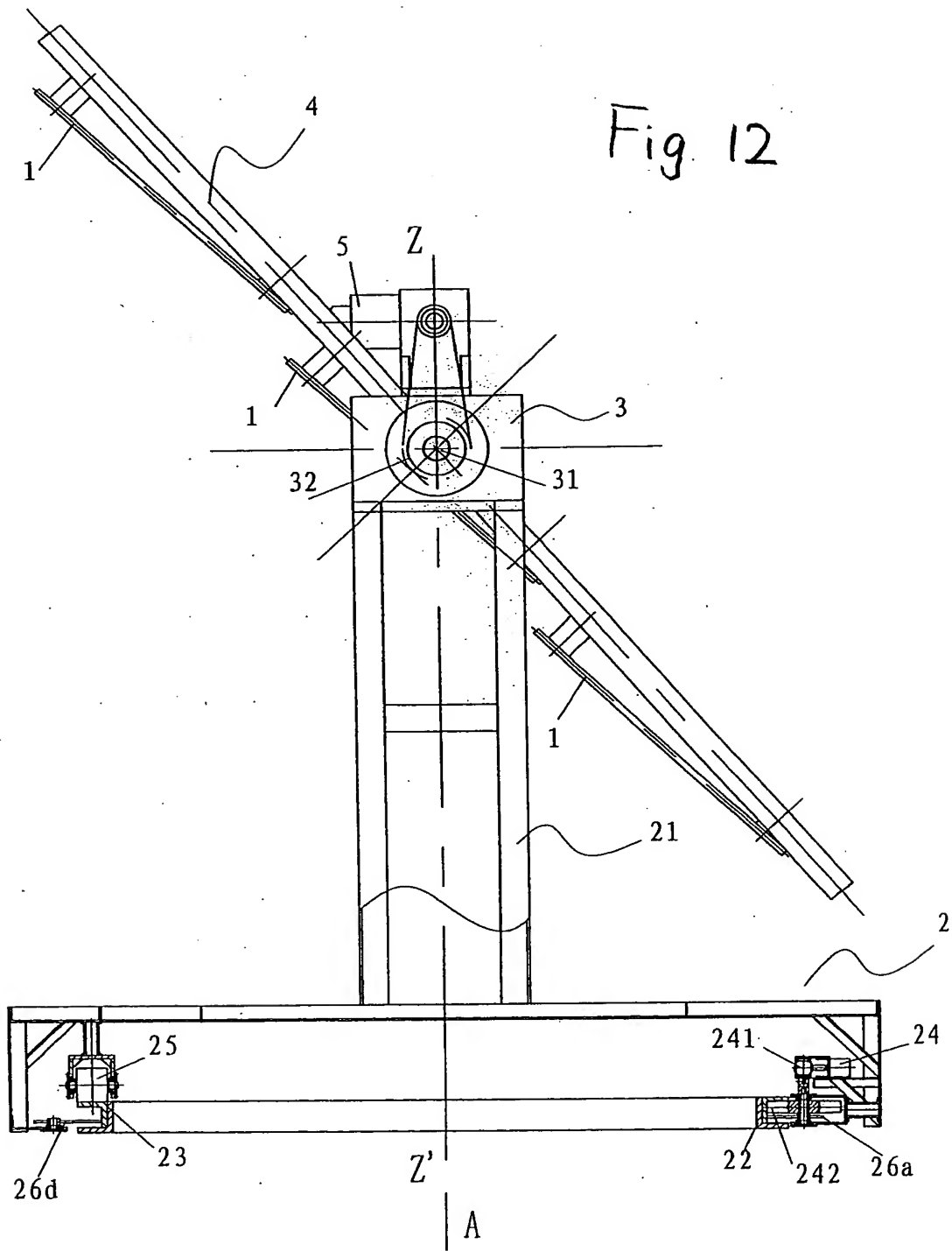


Fig. 11

Fig. 12



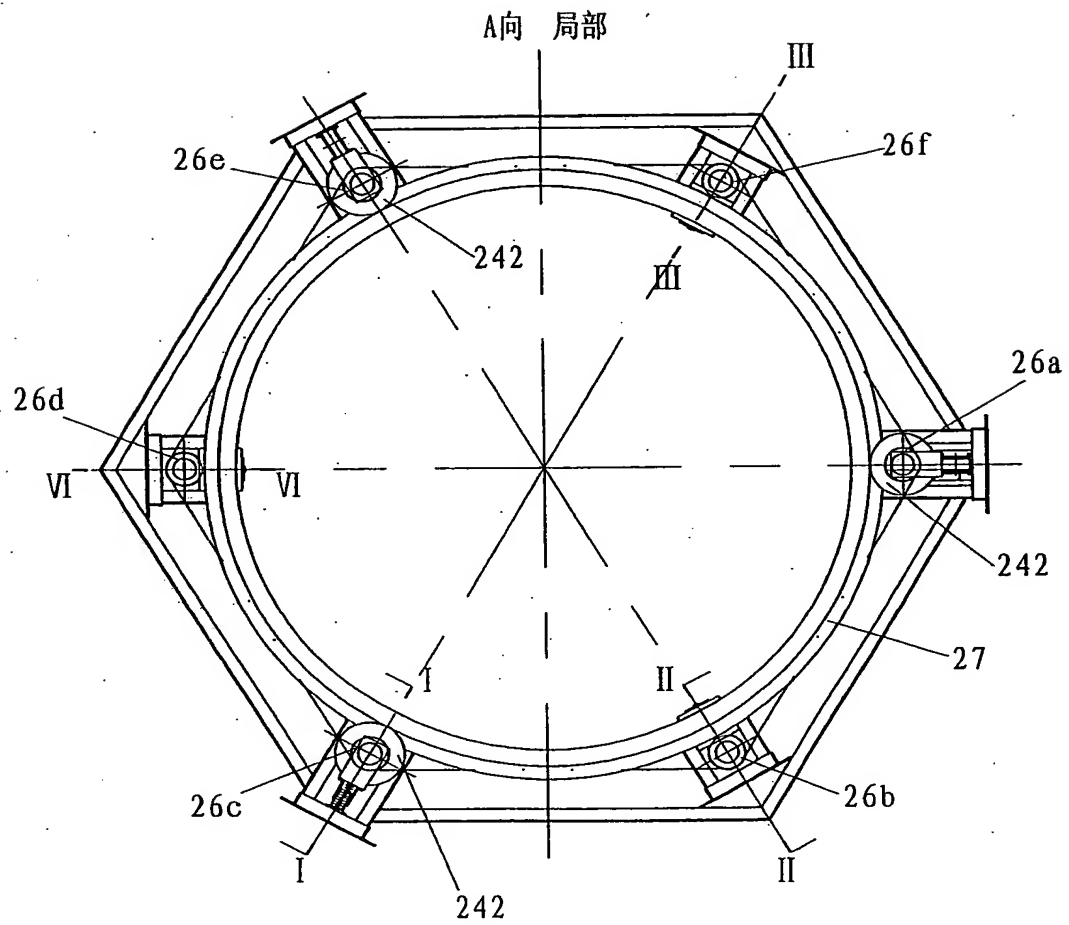


Fig. 13

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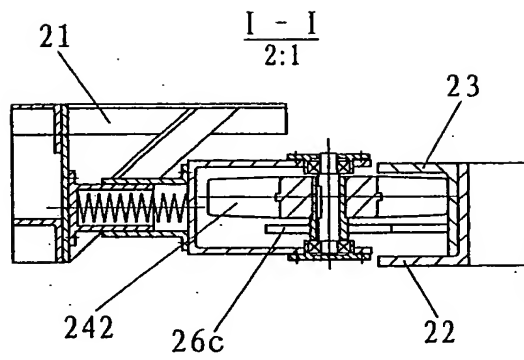


Fig. 14

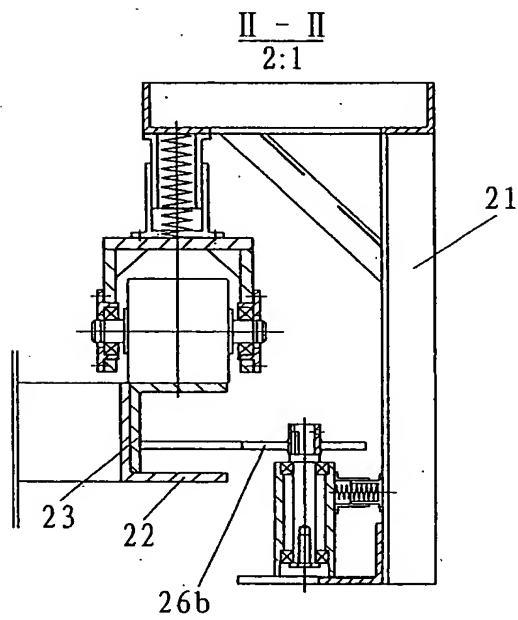


Fig. 15

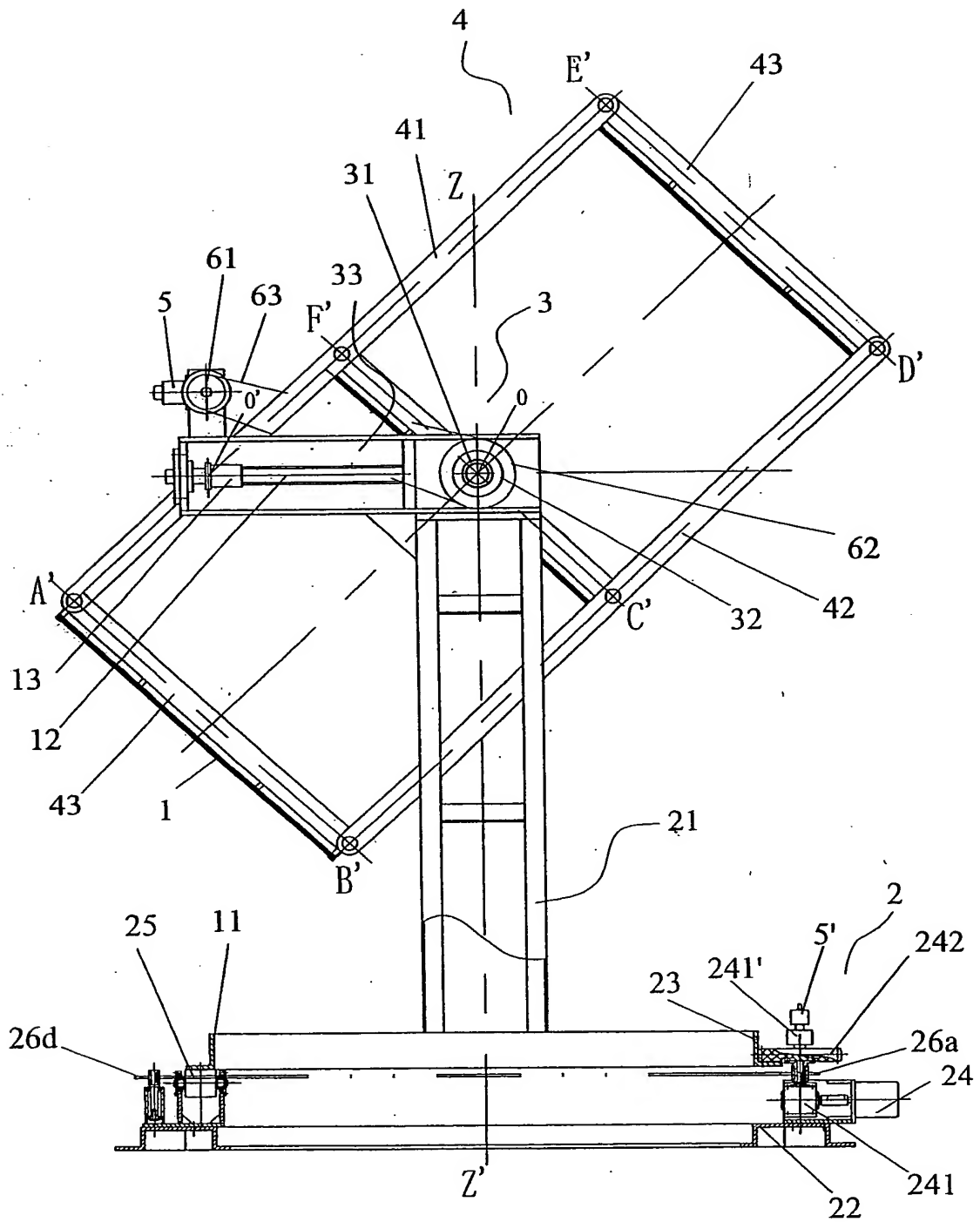


Fig. 16

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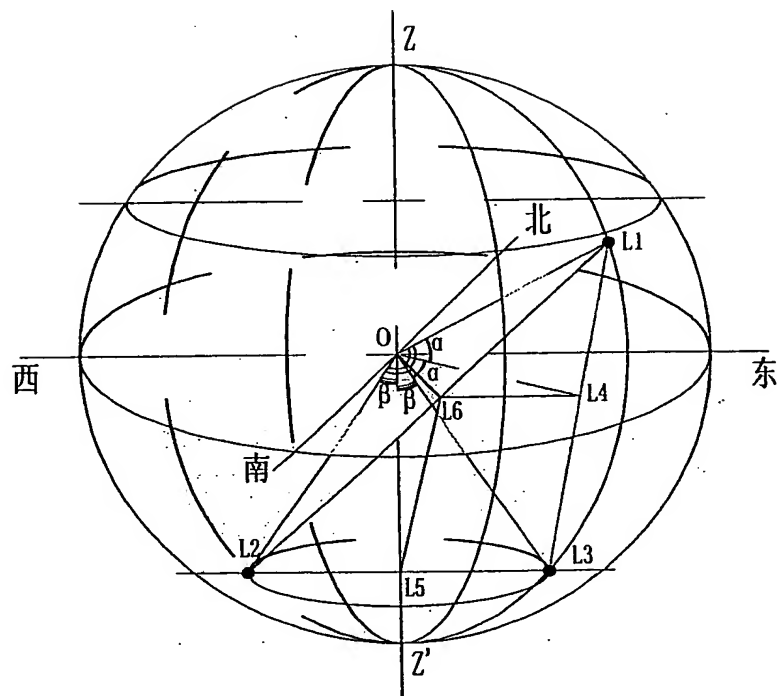


Fig. 17

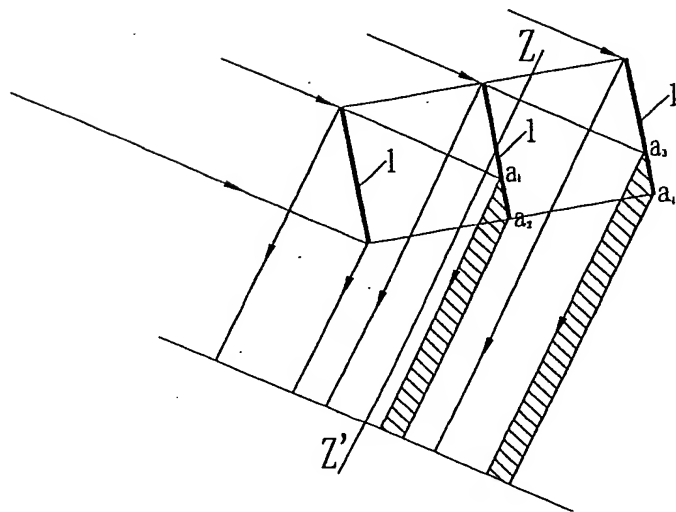


Fig. 18

Fig. 20

The diagram shows a mechanism with two links, 1 and 2, pivoted at a common point O_2 . Link 1 is a parallelogram with vertices O_1 , F' , and D' . Link 2 is a line segment from O_2 to O_1 . Arrows indicate angular velocities at O_1 and O_2 .